

L Number	Hits	Search Text	DB	Time stamp
1	65	(shekel and eyal).in.	USPAT; US-PPGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:05
2	4	(raphaeli same eli).in.	USPAT; US-PPGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:03
3	50	(matmon same guy).in.	USPAT; US-PPGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:04
4	2144	(356/399-401).CCLS.	USPAT; US-PPGPUB	2004/02/27 13:04
6	125	((((356/399-401,153,73.1).CCLS.) ((385/14,15,52).CCLS.) ((398/156,10,16,17).CCLS.) ((250/559.29,559.3,559.37).CCLS.)) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) ) and ((signal intensity) near (maxim\$ optim\$))	USPAT; US-PPGPUB	2004/02/27 13:28
5	186	((((356/399-401,153,73.1).CCLS.) ((385/14,15,52).CCLS.) ((398/156,10,16,17).CCLS.) ((250/559.29,559.3,559.37).CCLS.)) and ((rotat\$ revolv\$ angular\$ angl\$) near axi\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3))	USPAT; US-PPGPUB	2004/02/27 13:29
7	127	(356/154).CCLS.	USPAT; US-PPGPUB	2004/02/27 13:16
8	15	(250/227.3).CCLS.	USPAT; US-PPGPUB	2004/02/27 13:16
9	142	((356/154).CCLS.) ((250/227.3).CCLS.)	USPAT; US-PPGPUB	2004/02/27 13:17
10	2	((356/154).CCLS.) ((250/227.3).CCLS.) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	USPAT; US-PPGPUB	2004/02/27 13:37
11	2	((356/154).CCLS.) ((250/227.3).CCLS.) and ((rotat\$ revolv\$ angular\$ angl\$) near axi\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3))	USPAT; US-PPGPUB	2004/02/27 13:38
12	484	((356/153).CCLS.)	USPAT; US-PPGPUB	2004/02/27 13:34
13	7556	(g01N021/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:35
14	7472	(g01b011/26.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:35
15	1441	(g01c001/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:35
16	30190	(g01b011/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:35
17	6259	(g02b006/28.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:36

18	7714	(g02b006/26.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:36
19	17303	(g02b006/42.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:36
20	5078	(h04b010/08.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:36
21	14043	(h04b017/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:37
22	8582	(h04b010/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:37
23	109	(g01b009/10.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:37
24	428	(g01v008/00.ipc.)	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:37
25	1	((g01N021/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:39
26	0	((g01N021/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:39
27	1	((g01b011/26.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:41
28	10	((g01b011/26.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:41
29	3	((g01c001/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:41
30	2	((g01c001/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:42
31	1	((g01b011/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:42
32	7	((g01b011/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:43
33	1	((g02b006/28.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:43
34	0	((g02b006/28.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:43

35	0	((g02b006/26.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:43
36	1	((g02b006/26.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:44
37	0	((g02b006/42.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:44
38	0	((g02b006/42.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:44
39	0	((h04b010/08.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:44
40	0	((h04b010/08.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:45
41	2	((h04b017/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:45
42	0	((h04b017/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:45
43	1	((h04b010/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:45
44	0	((h04b010/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:46
45	0	((g01b009/10.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:46
46	0	((g01b009/10.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:46
47	0	((g01v008/00.ipc.) ) and (((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)) and ((signal intensity) near (maxim\$ optim\$)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:46
48	0	((g01v008/00.ipc.) ) and (((rotat\$ revolv\$ angular\$ angl\$) near axis\$) and ((two different another other plural\$) near (receiv\$ photoreceiv\$ photodetect\$ photosens\$3 sens\$3 detect\$3)))	EPO; JPO; DERWENT; IBM_TDB	2004/02/27 13:46